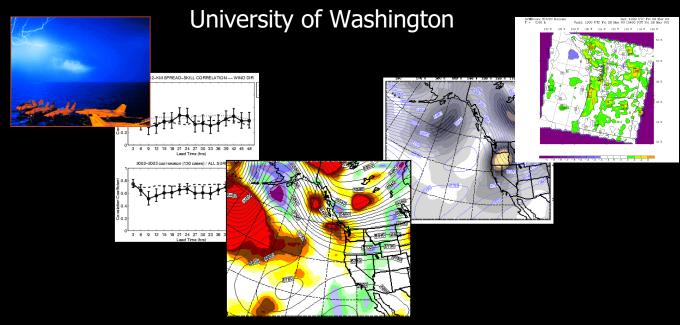
## Toward Short-Range Ensemble Prediction of Mesoscale Forecast Error

Eric P. Grimit and Clifford F. Mass





#### Supported by:

ONR Multi-Disciplinary University Research Initiative (MURI) and A Consortium of Federal and Local Agencies



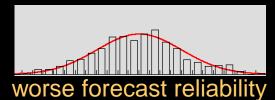
## <u>Traditional Approach – Spread-Error Correlation</u>

Ensemble spread should provide an approximation to the true forecast uncertainty

agreement

better forecast reliability

disagreement

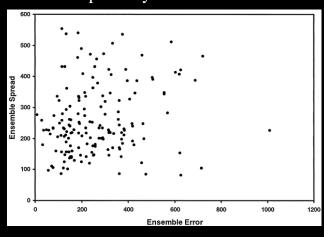


- To quantify this "spread-skill relationship":
  - Find the linear correlation between ensemble spread (σ) and the ensemble mean forecast error (|e<sub>EM</sub>|) over a large sample
  - Strength of the correlation is limited by the case-to-case spread variability (β) (Houtekamer, 1993; Whitaker and Loughe, 1998)

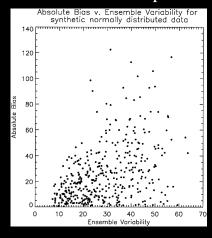
$$\rho^{2}(\sigma, |e_{EM}|) = \frac{2}{\pi} \frac{1 - \exp(-\beta^{2})}{1 - \frac{2}{\pi} \exp(-\beta^{2})}; \beta = \operatorname{std}(\ln \sigma)$$

# Observed Forecast Error Predictability: A Disappointment

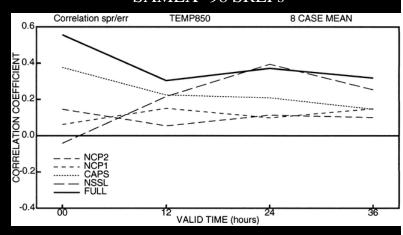
#### Tropical Cyclone Tracks



#### NCEP SREF Precipitation



SAMEX '98 SREFs



[c.f. Goerss 2000]

[c.f. Hamill and Colucci 1998]

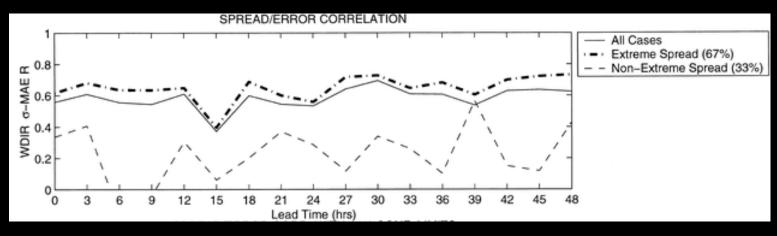
[c.f. Hou et al. 2001]

- Highly scattered relationships, thus low correlations
- No indication of spread-error correlation potential
- No assessment of dependency on the metrics used

# Observed Forecast Error Predictability: A Disappointment

Not all hope is lost...

UW MM5 SREF 10-m Wind Direction



[c.f. Grimit and Mass 2002]

- More recent studies show that domain-averaged spreaderror correlations can be as high as 0.6-0.7
  - (Grimit and Mass 2002, Stensrud and Yussouf 2003)
  - Potentially higher correlations can be achieved by considering only cases with extreme spread

## A Simple Stochastic Model of Spread-Skill

#### **PURPOSES**:

- 1) To establish <u>practical</u> limits of forecast error predictability, that could be expected given perfect ensemble forecasts of finite size.
- 2) To address the user-dependent nature of forecast error estimation by employing a variety of predictors and error metrics.

## A Simple Stochastic Model of Spread-Skill

1. Draw today's "forecast uncertainty" from a log-normal distribution (Houtekamer 1993 model).

In(
$$\sigma$$
) ~ N(In( $\sigma_f$ ),  $\beta^2$ )

2. Create synthetic ensemble forecasts by drawing M values from the "true" distribution.

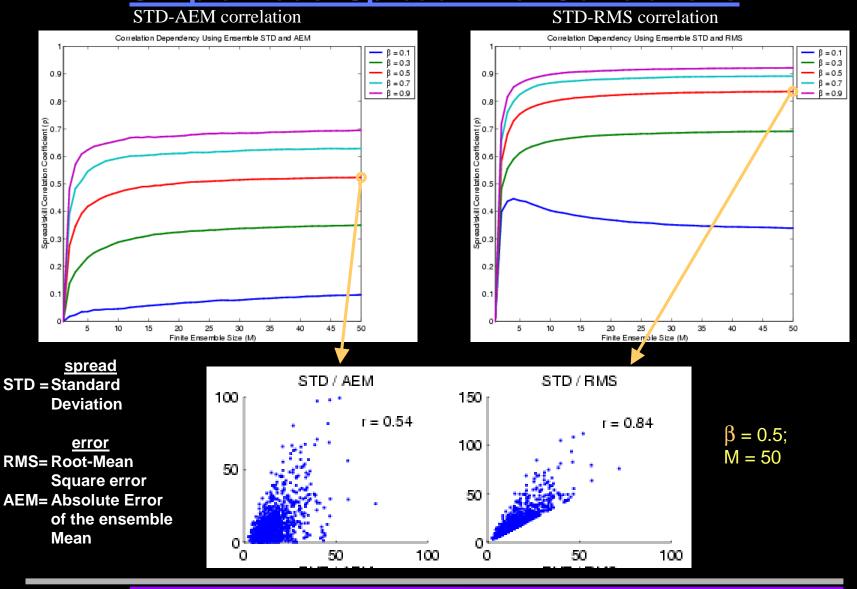
$$F_i \sim N(Z, \sigma^2)$$
;  $i = 1, 2, ..., M$ 

3. Draw the verifying observation from the same "true" distribution (statistical consistency).

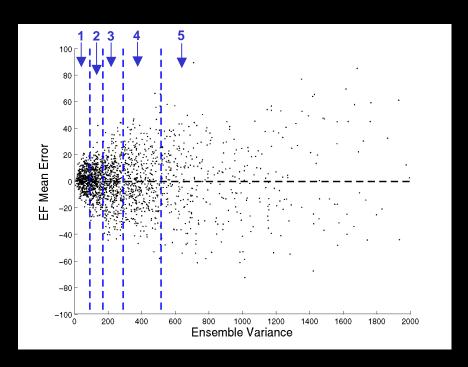
$$V \sim N(Z, \sigma^2)$$

- Stochastically simulated ensemble forecasts at a single, arbitrary observing location or model-grid box with 50,000 realizations (cases)
- Assumed:
  - Gaussian statistics
  - statistically consistent (perfectly reliable) ensemble forecasts
- Varied:
  - temporal spread variability (β)
  - finite ensemble size (M)
  - spread and skill metrics (continuous and categorical)

## **Simple Model Spread-Error Correlations**

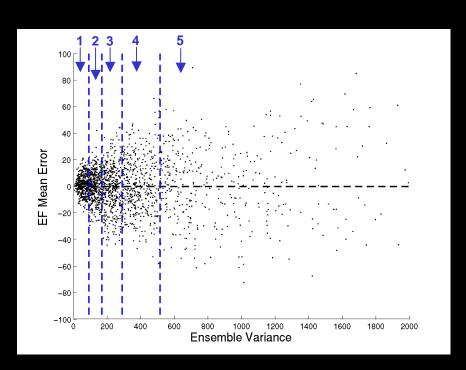


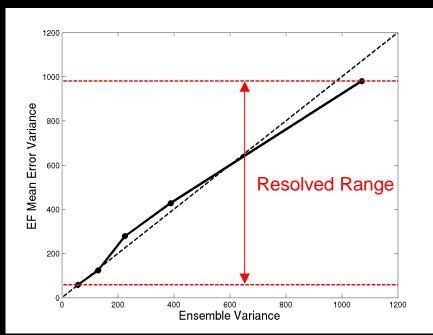
## **Alternative Approaches**



Given statistical consistency, ensemble variance should equal the EF mean forecast error variance.

## **Alternative Approaches**

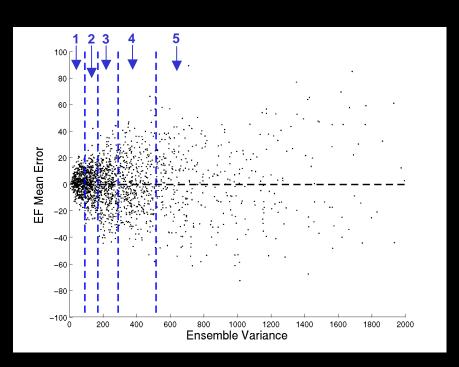


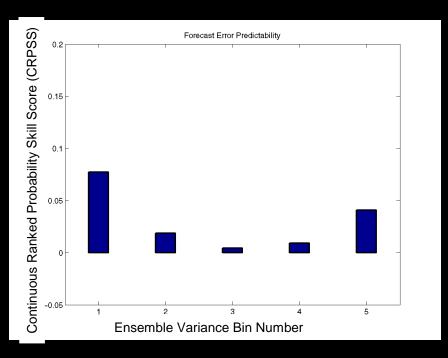


## Resolved range of error variance (Wang and Bishop 2003)

- Choose N<sub>bin</sub> equally populated bins of ensemble variance
- Find the mean ensemble variance and the error variance within each bin
- The range of resolved error variances indicates closeness to statistical consistency
- Could also be applied to other error metrics (e.g. AEM, RPS)

## **Alternative Approaches**





- Probabilistic skill of forecast error predictions
  - Use errors conditioned by spread category as probabilistic predictions of forecast error.
    - Evaluate using CRPS and its associated skill score with a cross-validation procedure.
    - CRPSS measures the continuous forecast error predictability.
  - For categorical error forecasts, use BS or RPS and the associated skill score.
  - Tradeoff between bin widths and number of samples in each bin.

## **UW SREF System Summary**

	Name	# of Members	EF Type	Initial Conditions	Forecast Model(s)	Forecast Cycle	Domain
Homegrown	ACME	17	SMMA	8 Ind. Analyses, 1 Centroid, 8 Mirrors	"Standard" MM5	00Z	36km, 12km
	ACMEcore	8	SMMA	Independent Analyses	"Standard" MM5	00Z	36km, 12km
	ACMEcore+	8	РММА	ee ee	8 MM5 variations	00Z	36km, 12km
ported	PME	8	МММА		8 "native" large-scale	00Z, 12Z	36km

**ACME:** Analysis-Centroid Mirroring Ensemble

PME: Poor-Man's Ensemble

SMMA: Single-Model Multi-AnalysisPMMA: Perturbed-Model Multi-Analysis

MMMA: Multi-model Multi-Analysis

## Mesoscale SREF and Verification Data



#### Mesoscale SREF Data:

- Total of 129, 48-h forecasts (31 OCT 2002 28 MAR 2003) all initialized at 0000 UTC
- Missing forecast case days are shaded
- Parameters of Focus:
  - 12 km Domain: Wind @ 10m (WDIR<sub>10</sub>, WSPD<sub>10</sub>) Temperature at 2m (T<sub>2</sub>)
- Short-term mean bias correction
  - Applied at every location and forecast lead time separately
  - Varied training window from 2-30 days

#### Verification Data:

12 km Domain:

RUC20 analysis

(NCEP 20 km mesoscale analysis)

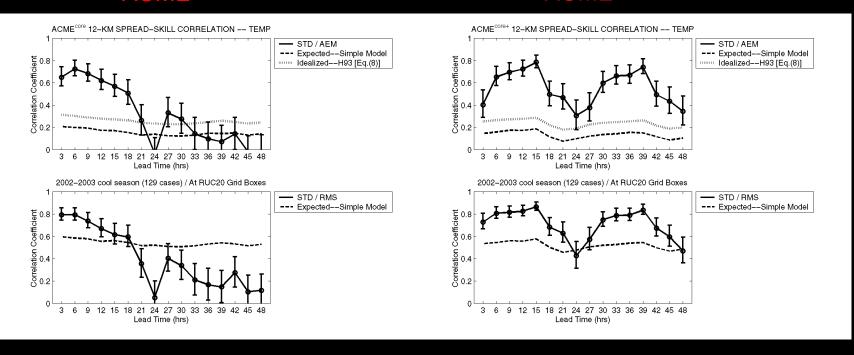
observations

## **Domain-Averaged Spread-Error Correlation**

(no bias correction)

#### ACMEcore

#### ACMEcore+



- The benefit of including model physics variability is apparent.
- Domain-averaging produces correlations much higher than expected. Correlations of averages are referred to as ecological correlations in statistics.

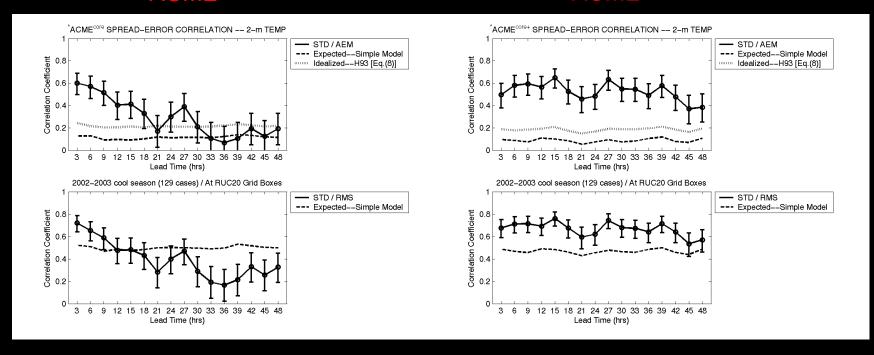


## **Domain-Averaged Spread-Error Correlation**

(14-day bias correction)

#### \*ACMEcore

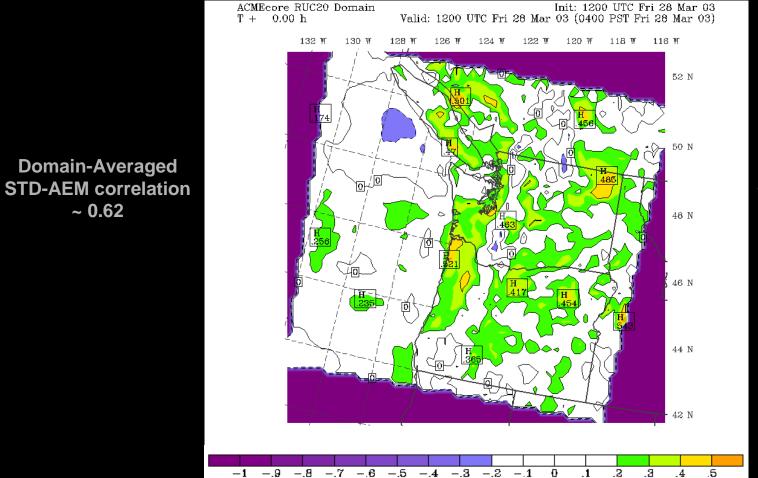
#### \*ACMEcore+



Bias correction reduces case-to-case spread variability, resulting in poorer spread-error correlations overall.



## **Spatial Distribution of Local Spread-Error Correlation**



**Maximum Local STD-AEM correlation**  $\sim 0.54$ 



**Domain-Averaged** 

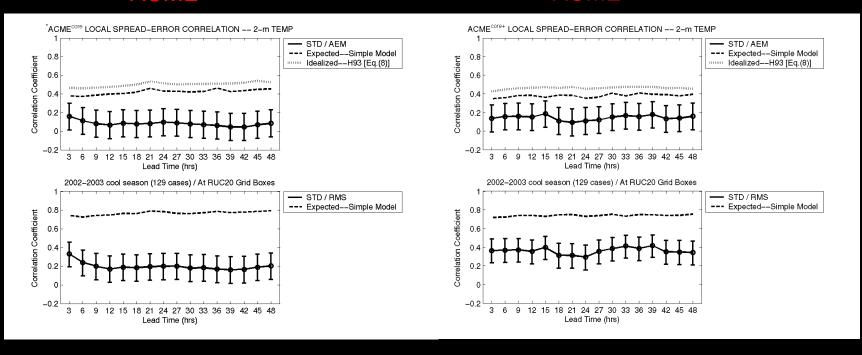
~ 0.62

## **Average Local Spread-Error Correlation**

(no bias correction)

ACMEcore

ACMEcore+



- The average local spread-error correlations are small.
- Estimates from the simple stochastic model are more applicable here, giving an indication of the departure from local statistical consistency.



## **Preliminary Conclusions**

- Accounting for model and surface boundary parameter uncertainty in a mesoscale SREF system is crucial.
  - ACME<sup>core+</sup> forecasts possess valuable information about the flow-dependent mesoscale uncertainty that ACME<sup>core</sup> forecasts do not.
- Eckel and Mass (2003) found that a simple bias correction improves ensemble forecast skill, but these results suggest that degradations are also possible.
  - Traditional spread-error correlations are reduced in many cases
  - A shorter range of error variances are resolved (F00-F15)
- Continuous (categorical) predictors of forecast error are most appropriate for end users with a continuous (categorical) utility function.

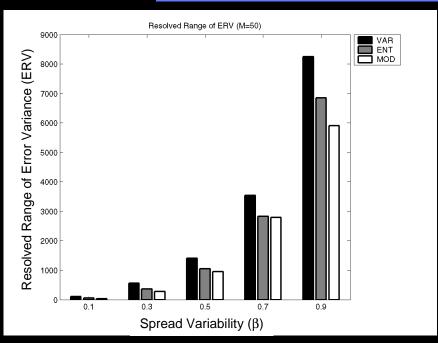
## **Outstanding Questions**

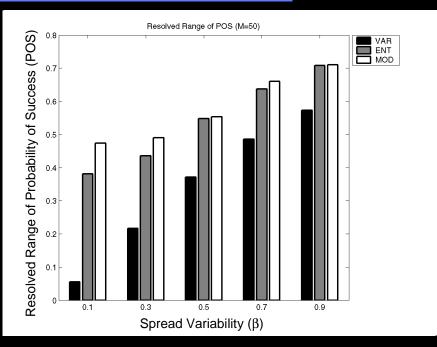
- How can an ensemble-based prediction system for <u>local</u> forecast errors be developed?
  - Ecological (domain-averaged) spread-error correlations can be quite large, while local spread-error correlations are near zero.
  - Can we ever expect local statistical consistency?
- Will more sophisticated post-processing methods (e.g. ensemble MOS, best-member dressing, Bayesian model averaging) also degrade the forecast error predictability?
  - Or is the decrease in forecast error predictability in this study an aberration?
  - Maintaining case-to-case spread variability must be a constraint of paramount importance for ensemble post-processing methods.

### **FURTHER QUESTIONS???**

# **EXTRA SLIDES**

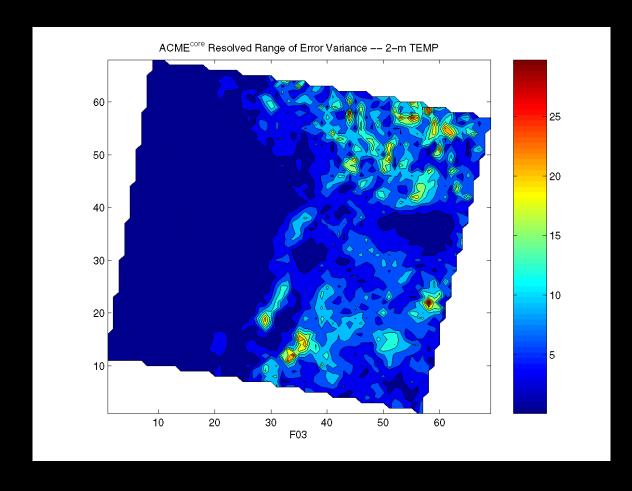
## **Continuous or Categorical Predictors?**





Continuous (categorical) predictors of forecast error are most skillful for end users with a continuous (categorical) utility function.

# **Spatial Distribution of Resolved Range of ERV**



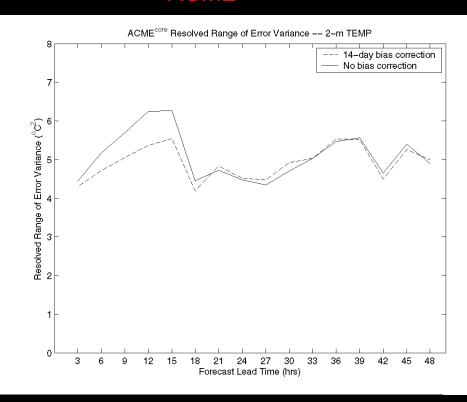


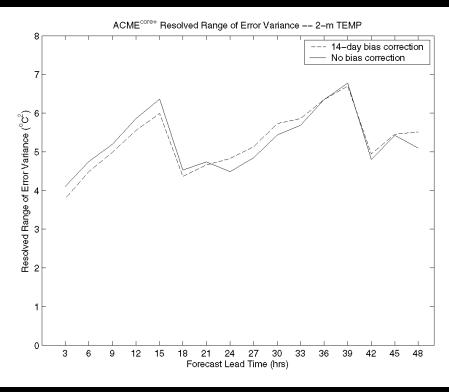
## Resolved Range of Local Error Variance

(Domain-averaged)

**ACME**core

ACMEcore+





Bias correction reduces the resolved range of local error variances during the first 15h. At longer lead times, no difference is apparent.

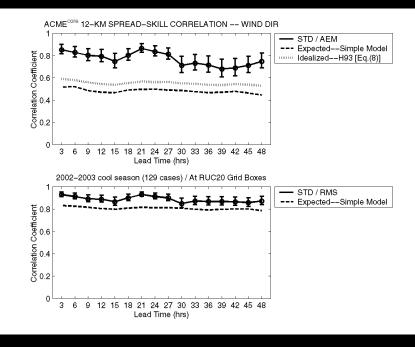


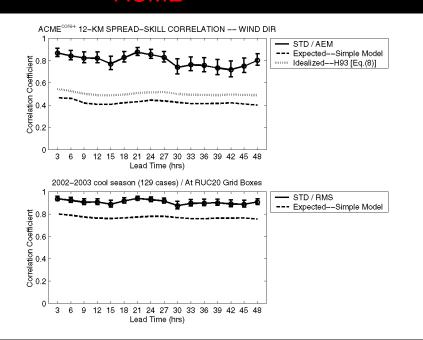
## **Spread-Error Correlations**

(no bias correction)

#### **ACME**core

#### ACMEcore+







## **Forecast Error Prediction**

Like any other scientific prediction or measurement, weather forecasts should be accompanied by error bounds, or a statement of uncertainty.

$$T_{2m} = 3 \, ^{\circ}C \,$$

- Forecast uncertainty changes spatially and temporally, and is dependent on:
  - Atmospheric predictability a function of the sensitivity of the flow to:
    - Magnitude/orientation of initial state errors
    - Numerical model errors / deficiencies
- Ensemble weather forecasts appear well-suited for quantifying fluctuations in atmospheric predictability

## Value of Forecast Error Prediction

- Operational forecasters require explicit prediction of this flow-dependent forecast uncertainty
  - Helps to decide how much to trust model forecast guidance
  - Current uncertainty knowledge is partial, and largely subjective
- End users could greatly benefit from knowing the expected forecast error
  - Allows sophisticated users to make optimal decisions in the face of uncertainty (economic cost-loss or utility)

Take protective action if:  $P(|E_{T_{2m}}| > 2 \text{ °C}) > \text{cost/loss}$ 

■ Common users of weather forecasts – confidence index



